Optimal managing of forest composition using data simulated optimal control

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Forestry situation in the Czech Republic



- 33 % of the Czech country forested
- economic importance for rural communities
- replacing natural ecosystems by spruce
- lack of biodiversity
- soil damage

Motivation

Composition of tree species in the Czech Republic



- need for forest composition modification
- legislative and subsidy measures

• unknown long run impacts

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Research aims

- to model long run impacts of current measures via dynamic optimization
- to estimate valid underlying functions
- to complete the data through simulation
- to develop the model in two stages
 - coarse version ("average" characteristics)
 - fine version (local specific characteristics)

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The simple optimal control problem

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max
$$V = \int_0^T \Pi(x, u, t) e^{-\rho t} dt$$
 (1)
s.t.
 $\dot{x} = f(t, x, u),$ (2)
 $x(0) = A$ given, $x(T) =$ free (3)
and additional constraints

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V objective functional ($\Pi(t)$ - total profit) $x_i(t)$ state variables $u_i(t)$ control variables

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The Drahanska highlands case

Area localization in the Czech Republic



- 72122 ha of forest land
- legislative: min 25 % reforested by soil improving species (SIS)

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- subsidies for:
 - seedlings (oak, beech),
 - intensive reforesting with SIS (above 30 %)

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Assumptions and restrictions

- not consider forestation of non-forest land
- substituting other species for spruce: only area of spruce may decrease in time
- changing forest composition after clear cutting spruce at rotation age
- current profit maximization:
 - revenues (timber selling, subsidies)
 - costs (planting, forest stand care, harvesting)

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The elements of optimization model

- state variables x_{it} area forested by tree species *i* in time *t*, t = 1, ..., T
- control variable u_{it} change in total area forested by species i in year t
- equation of motion $x_{i(t+1)} = x_{it} + u_{it}$
- objective function

$$F = \sum_{t=1}^{T} \delta^{t} \left[\sum_{i=1}^{n} \left(G_{it} - K_{it} + \sigma_{i} u_{it} \right) + \sum_{k=1}^{5} \rho_{k} w_{kt} \right]$$

$$G_{it} = g_{i0} + g_{i1}x_{it} + \frac{1}{2}g_{i2}x_{it}^{2}$$

$$K_{it} = k_{i} + a_{i}x_{it} + b_{i1}u_{it} + \frac{1}{2}b_{i2}u_{it}^{2}$$

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The complete dynamic optimization model

$$\begin{aligned} \max_{x_{it}, u_{it}, w_{kt}} & F = \sum_{t=1}^{T} \delta^{t} \left[\sum_{i=1}^{n} \left(G_{it} - K_{it} + \sigma_{i} u_{it} \right) + \sum_{k=1}^{5} \rho_{k} w_{kt} \right] \\ \text{s.t.} & x_{i(t+1)} = x_{it} + u_{i(t+1)} \\ & \sum_{i=1}^{n} x_{it} = A \text{ for all } t \\ & \sum_{i=1}^{4} u_{jt} \le x_{5(t-1)} / \tau_{5} \\ & u_{1t} + u_{2t} + u_{4t} \ge 0.25 x_{5(t-1)} / \tau_{5} \\ & \sum_{k=1}^{5} \rho_{k} w_{kt} = u_{1t} + u_{2t} + u_{4t} \\ & \sum_{k=1}^{5} \rho_{k} w_{kt} = x_{5t} / \tau_{5} \\ \text{and} & x_{i0} \text{ given, } x_{iT} \text{ free, } x_{it}, u_{jt} \ge 0, \ 1 \le i, k \le 5, , \ 1 \le j \le 4. \end{aligned}$$

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Estimating revenue and cost functions

$$G_{it} = g_{i0} + g_{i1}x_{it} + \frac{1}{2}g_{i2}x_{it}^{2}$$

$$K_{it} = k_{i} + a_{i}x_{it} + b_{i1}u_{it} + \frac{1}{2}b_{i2}u_{it}^{2}$$

- real data on environmental, technological and economical characteristics from public sources and Mendel university forest enterprise.
- in original form not sufficient for estimation of the cost and revenue functions parameters.
- it is possible to obtain such estimates using extensive simulation.
- totally 100,000 combinations of necessary values were simulated.

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Time path for forest composition



- replacing spruce by oak: by minimal admissible speed
- different long run subsidy scenarios: no effect

Conclusion and future work

- revenue and cost functions: realistic representation
- first stage (coarse) model: results correspond to the observed situation
- second stage model:
 - incorporate fine structure of the Drahanska highlands area
 - simulation based on particular local characteristics (terrain profile, over sea altitude, soil quality,...)
- subsidy policy optimization

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Thank you.

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