

A hierarchical Markov decision process modelling feeding and marketing decisions of growing pigs

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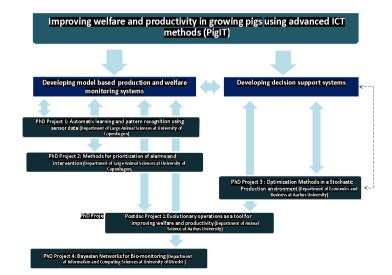
Agenda

PigIT research group

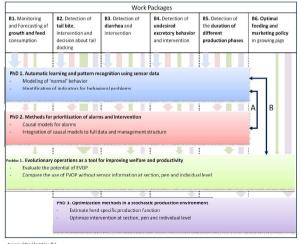
Optimal feeding and marketing decisions
Problem definition
Modelling approach
Initial results

Further research

PigIT project



Work packages



Source: http://pigit.ku.dk/



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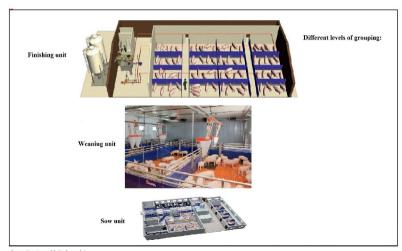
A sub-project in the work package B6

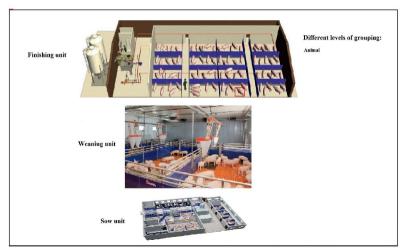
A hierarchical Markov decision process modelling feeding and marketing decisions of growing pigs

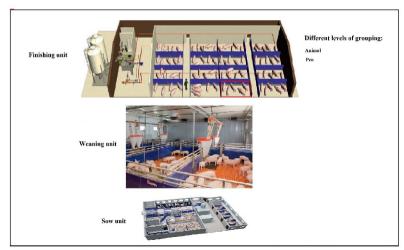
Contributions:

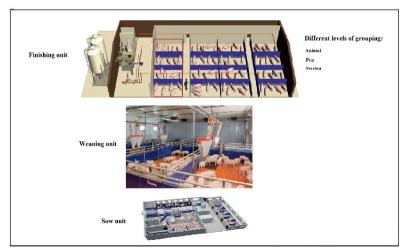
- ► Combination of feeding and marketing decisions by a hierarchical Markov decision process (HMDP).
- Embedding a dynamic linear model (DLM) and a dynamic generalised linear model (DGLM) into the proposed HMDP.



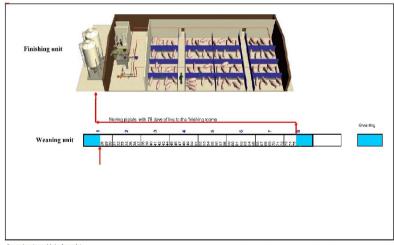




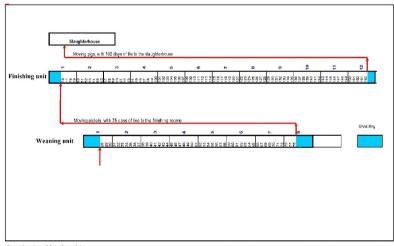


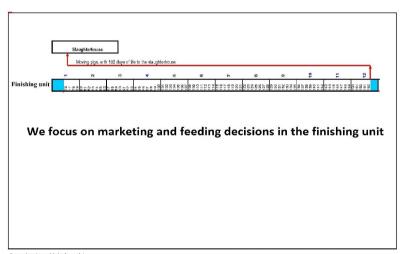




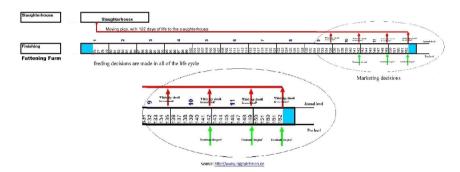








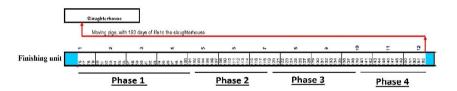
Problem definition - Marketing decisions



- ▶ Pen (or section) level: decision about when to terminate a pen and insert a new group of piglets to the pen.
- ▶ Individual (Animal) level: decisions about how to select and when to market individual animals for slaughter.

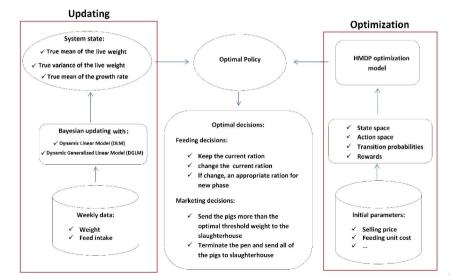
Problem definition - Feeding decisions

Phase feeding



- ▶ Decision about the time that the current ration (in the current phase) should be changed.
- Decision about finding the best new ration in the next phase.

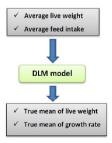
Modelling approach - framework (pen level)

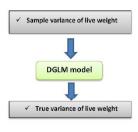


Updating model - Observations

The observations in the pen for each week (or day):

- ▶ Average live weight
- ► Sample variance of the live weight
- ► Average feed intake





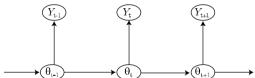
▶ DLM is a statistical model to analyse the time series and extract the true trend of latent variables (θ_t) based on the observed data:



► A system equation describes the extension of the latent variable against time t:

$$\theta_t = G\theta_{t-1} + \omega_t, \ \omega_t \sim N(0, V_t)$$

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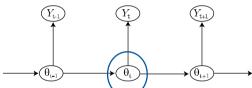
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▶ An observation equation indicates the relation between the observable (Y_t) and latent (θ_t) variables:

$$Y_t = F'\theta_t + \nu_t, \ \nu_t \sim N(0, W_t)$$

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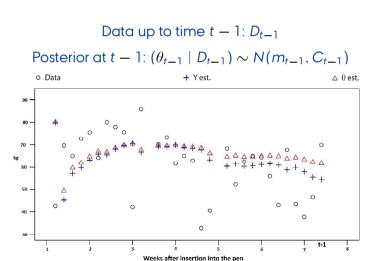
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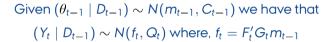
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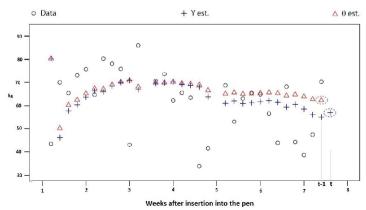
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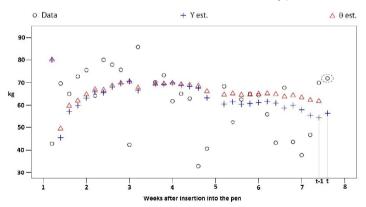
- $ightharpoonup W_{t-f}$: Average live weight at time t
- $ightharpoonup FE_{t,f}$: Average feed intake in interval [t, t+1]
- $ightharpoonup TW_{t,f}$: True live weight at week t
- $ightharpoonup Z_{t,f}$: True growth rate at time t
- ► V: System variances (constant) estimated by EM algorithm
- ▶ W: Observation variances (constant) estimated by EM algorithm



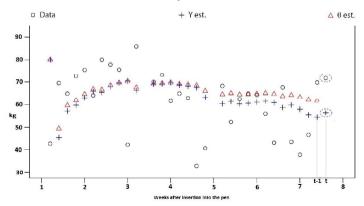




At time t we see an observation y_t :

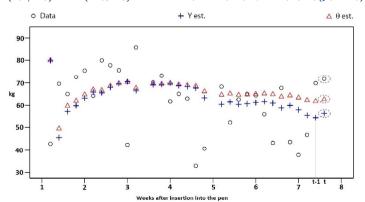


Given f_t and y_t we have that



Given f_t and y_t we have that

$$(\theta_t \mid D_t) \sim N(m_t, C_t)$$
 where, $m_t = G_t m_{t-1} + R_t F_t Q_t (y_t - f_t)$



Observation equations:

$$f(s_t^2|\eta_t) = \frac{\exp(\frac{-s_t^2(n_t-1)}{2\sigma_t^2})(\frac{n_t-1}{2\sigma_t^2})^{\frac{n_t-1}{2}}(s_t^2)^{\frac{n_t-3}{2}}}{\Gamma(n_t-1)}$$
$$g(\eta_t) = \sigma_t^2$$

where $g(x) = \frac{1}{x}$ System equations:

$$\sigma_t^2 = G_t \sigma_{t-1}^2$$

- $ightharpoonup s_t^2$: Sample variance of the live weights in pen.
- σ_t^2 : True variance of the live weight in the pen.

 $ightharpoonup n_t$: Number of pigs in the sample for s_t^2

Updating model - Validating the DLM

- ► To validate the DLM model, the observations were generated by a simulation approach and we supposed the true means are given in this step.
- ► The filtered data (output of the DLM model) show a good prediction of the true means of the live weight and the true means of the growth rate in the pen.
- ▶ Initial results indicate a good learning capability of the suggested DLM model.

